

# The Silicon Vertex Detector of the Belle II Experiment

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on behalf of the Belle II SVD collaboration

September 25, 2023



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# Outline

- 1 Belle II experiment & Silicon Vertex Detector
- 2 SVD operation status and performance
- 3 Software developments toward high luminosity
- 4 LS1 activity
- 5 Summary

# Silicon Vertex Detector in Belle II experiment

- Belle II experiment at luminosity frontier in search for new physics beyond standard model
- **SuperKEKB** collider: Asymmetric  $e^+e^-$  collisions at  $\Upsilon(4S)$  resonance at 10.58 GeV
- **Vertex Detector (VXD)** sits nearest to the interaction point with total 6 Layers
  - Inner 2 layers of **Pixel Detector (PXD)**: DEPFET pixel sensor
  - 4 layers of **Silicon Vertex Detector (SVD)**: Double-sided strip
  - Requirements: excellent vertex resolution and operation in a high-background environment

## Target

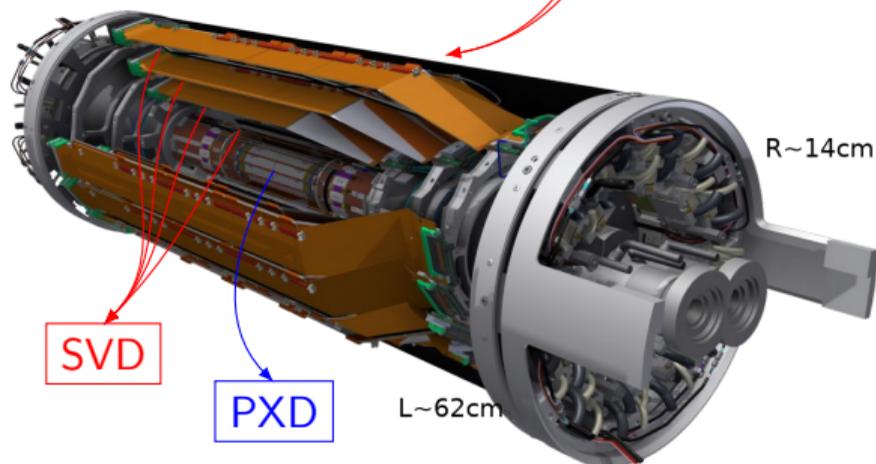
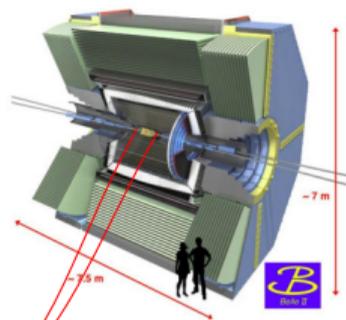
$$\int \mathcal{L} dt = 50 \text{ ab}^{-1}$$

$$\mathcal{L} = 6 \times 10^{35} \text{ cm}^{-2} \text{ s}^{-1}$$

## Achieved

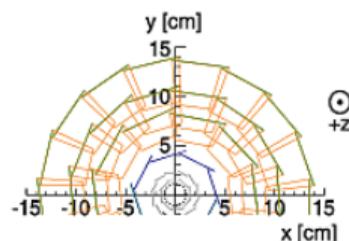
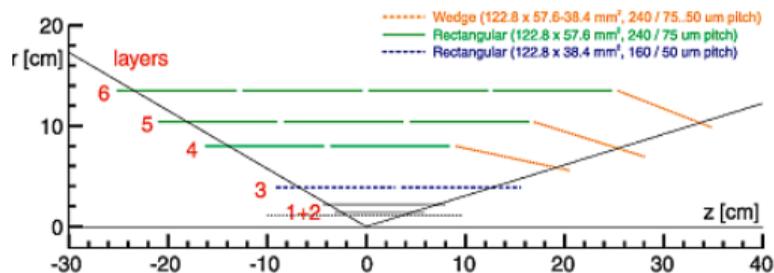
$$\int \mathcal{L} dt = 424 \text{ fb}^{-1}$$

$$\mathcal{L} = 4.7 \times 10^{34} \text{ cm}^{-2} \text{ s}^{-1}$$



# Main SVD features

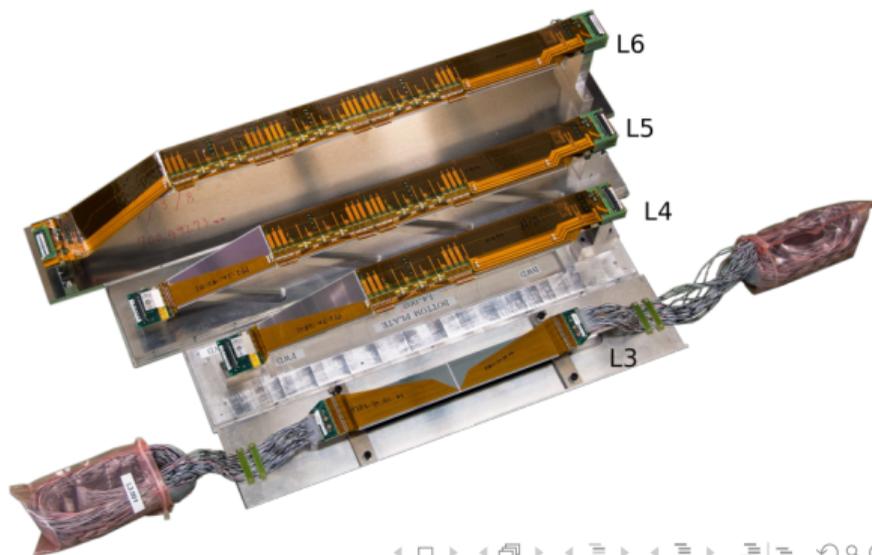
- Standalone tracking for low momentum tracks and precise vertexing of  $K_S$
- Extrapolate tracks to PXD
- Provide particle identification using  $dE/dx$ .



SVD sensors are organised in electrically and structurally independent **ladders**

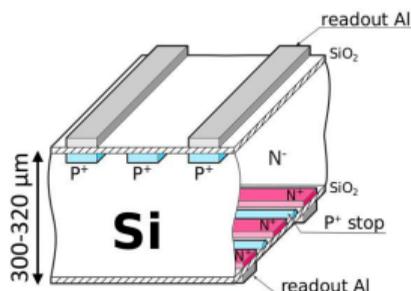
Layer	Ladder	Sensors per Ladder	Radius (mm)
3	7	2	39
4	10	3	80
5	12	4	104
6	16	5	135

- Forward sensors are slanted to maximise acceptance with smaller incidence angle
- Low material budget of 0.7%  $X_0$  per layer



# SVD sensors & front-end

- Double-sided Silicon Strip Detectors (DSSD): provides 2D spatial information:  
u/P-side  $\rightarrow r\phi$ , v/N-side  $\rightarrow z$
- 172 sensors with 224k readout strips covering 1.2 m<sup>2</sup>
- Readout chip on top of sensor: origami concept
- 3 different types of DSSD shapes

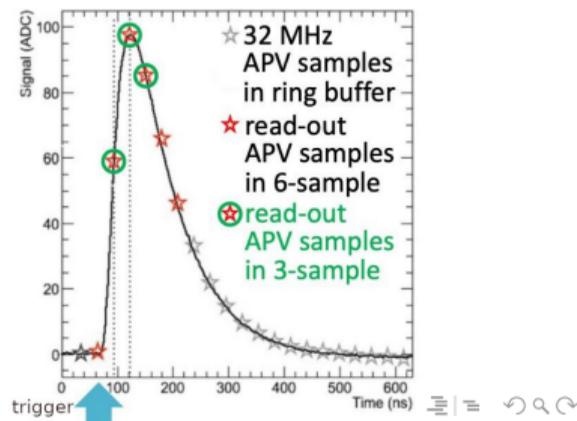


	Small	Large	Trapezoidal
# of p-strips*	768	768	768
p-strip pitch*	50 $\mu\text{m}$	75 $\mu\text{m}$	50-75 $\mu\text{m}$
# of n-strips*	768	512	512
n-strip pitch*	160 $\mu\text{m}$	240 $\mu\text{m}$	240 $\mu\text{m}$
thickness	320 $\mu\text{m}$	320 $\mu\text{m}$	300 $\mu\text{m}$
manufacturer	HPK		Micron

\*readout strips – one floating strip on both sides

## Front-end ASIC APV25

- Radiation hard: >100 Mrad
- Fast pulse shaping time of 50 ns
- Power consumption: 0.4 W/chip
- 128 channels per chip
- Multi-peak mode at 32 MHz
  - Records 6 samples
  - 3/6-mixed acquisition also ready for high luminosity runs



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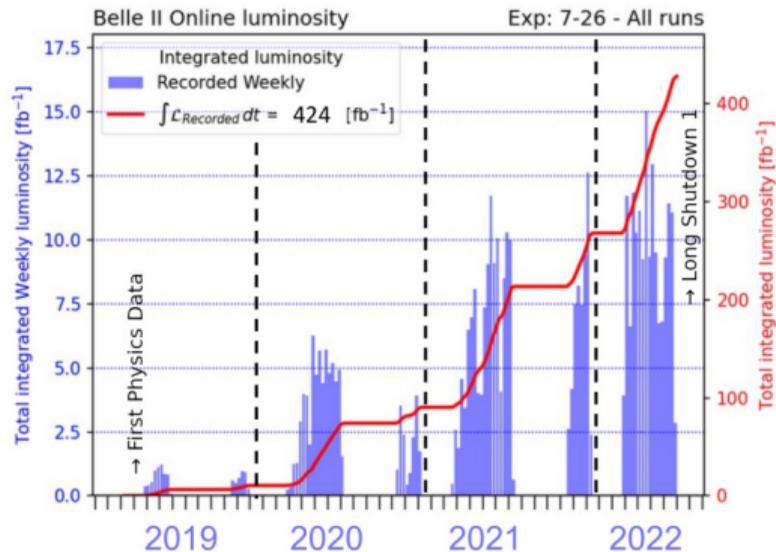
# SVD operation status

## Timeline

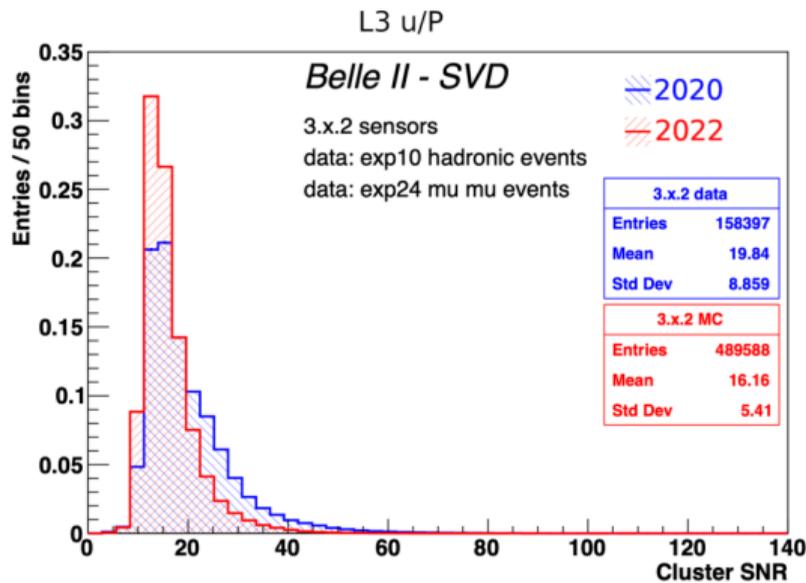
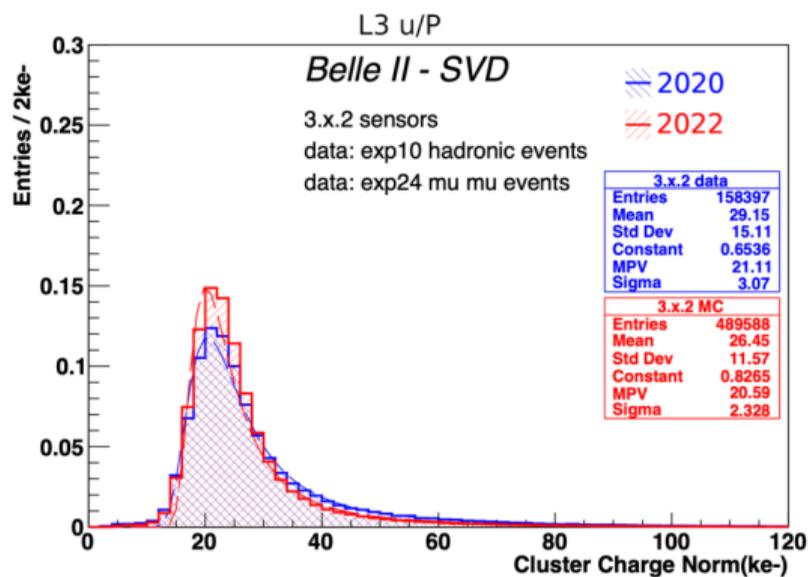
- **March 2019:** First Physic Data with VXD
- **July 2022:** Long-Shutdown (LS1) activity
  - Accelerator and detector maintenance & improvements
  - **VXD upgrade** with new PXD + current SVD
- **December 2023:** Resume beam operation

## Smooth and stable operation without major issues

- Masked strips are less than 1%
- Stable environment and calibration constants' evolution consistent with expectation
- Excellent detector performance  $\implies$  Good signal-to-noise ratio (SNR), precise position resolution and large hit efficiency ( $>99\%$ )
- Background effects are well under control



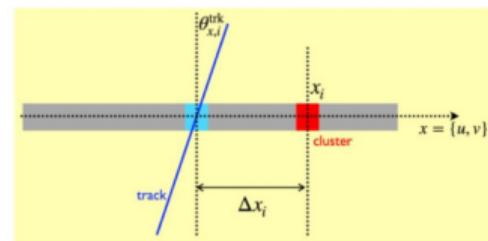
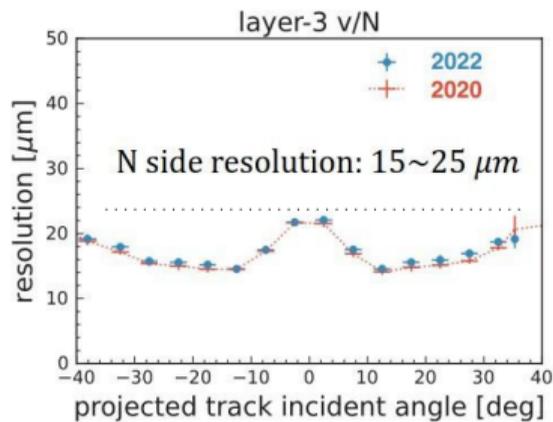
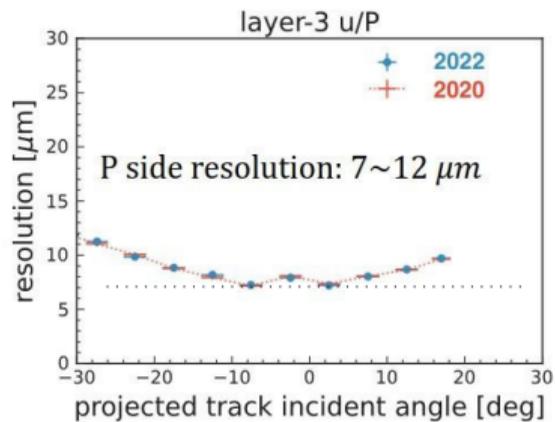
# SVD cluster charge & SNR



## Good stability of cluster charge and SNR from 2020 & 2022

- Cluster charge normalised to track length similar in all sensors
- Small changes observed in SNR due to noise increase by radiation damage, as expected
  - MPV 13-30 depending on sensor position

# SVD cluster position resolution



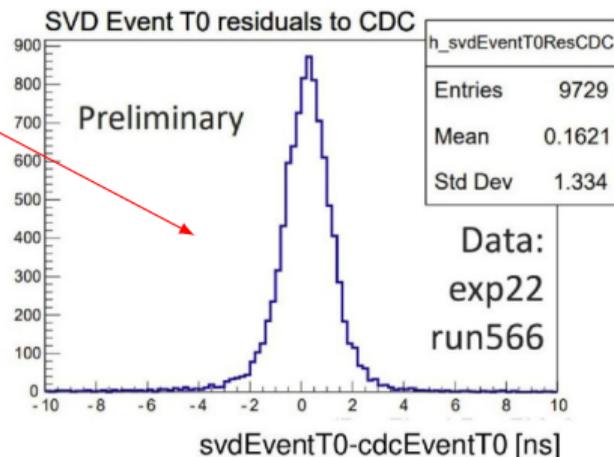
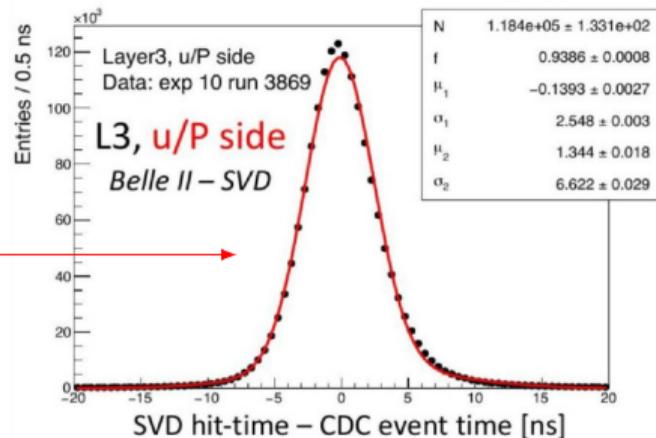
$$\sigma_x = \sqrt{\langle (\Delta x_i)^2 - (\sigma_{x,i}^{\text{trk}})^2 \rangle}$$

■  $\sigma_{x,i}^{\text{trk}}$  = unbiased track position error

- Position resolution is calculated from the cluster position with respect to the track extrapolation using  $e^+e^- \rightarrow \mu^+\mu^-$  sample.
- Stable position resolution is observed during the operation.
- Good resolution, generally as expected with pitch expectations (dotted line)

# SVD time resolution

- Excellent **cluster time** resolution of less than 3 ns
  - SuperKEKB bunch spacing:  $\sim 6$  ns
  - SVD acquisition window:  $\sim 100$  ns
- **Track time** is computed using all the hits on a tracks.
- **Event-time** in SVD is computed using all the clusters associated to selected tracks in an event.
  - The computation of event-time in SVD is  $\sim 2000$  times faster than the same from CDC
  - This feature speeds up the High Level Trigger (HLT) reconstruction helping it cope higher luminosity.

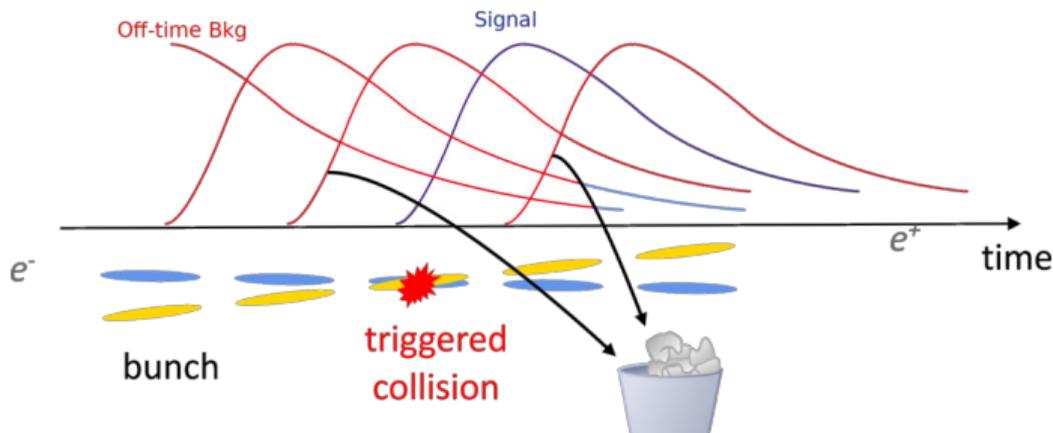


# Outline

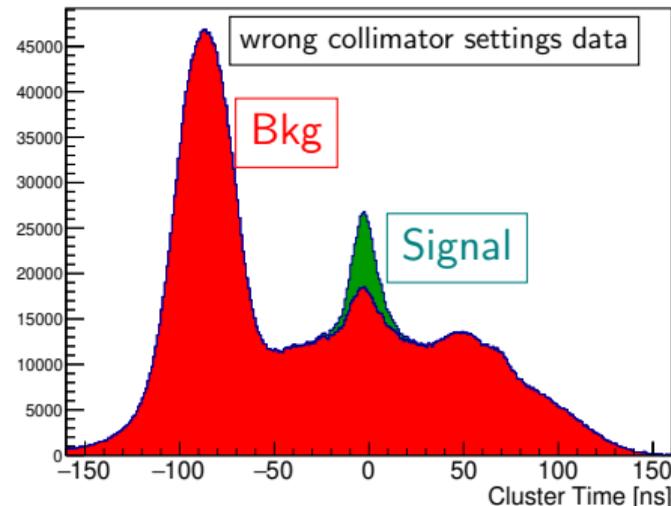
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# Reconstruction at high luminosity

- High luminosity comes with high beam backgrounds
- The accurate SVD time will be crucial in rejecting background and will allow to maintain the current excellent tracking performance
  - hit-time-based selection to remove off-time clusters
  - cluster time used to find suitable  $u/v$  pairs
  - tracking filters are trained with cluster time information



## SVD hit-time: all clusters

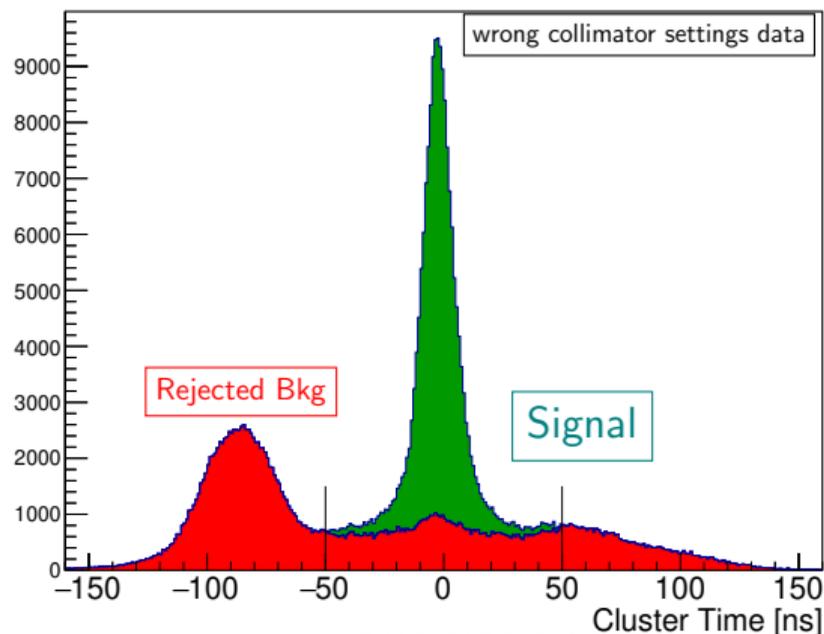


note: these data have been taken with wrong collimator settings and are affected by extremely high bkg and only chosen to illustrate the impact of time selection

# Background rejection with SVD hit-time selection

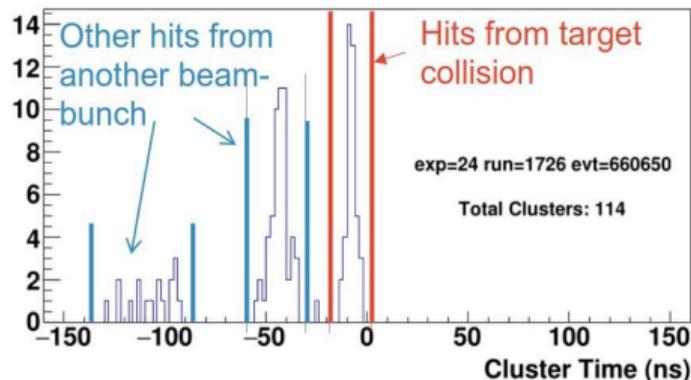
- Large contamination of **off-time clusters** in **tracks** if SVD time is not used in reconstruction
- The time-based hit selection and tracking filters reject the majority of the bkg while keeping above 99% of signal
  - $|t_{u,v}| < 50$  ns &  $|t_u - t_v| < 20$  ns
- Exploiting SVD time, the SVD Occupancy limit can be set at 4.7%.
  - There are still room for improvement

SVD hit-time: clusters-on-tracks

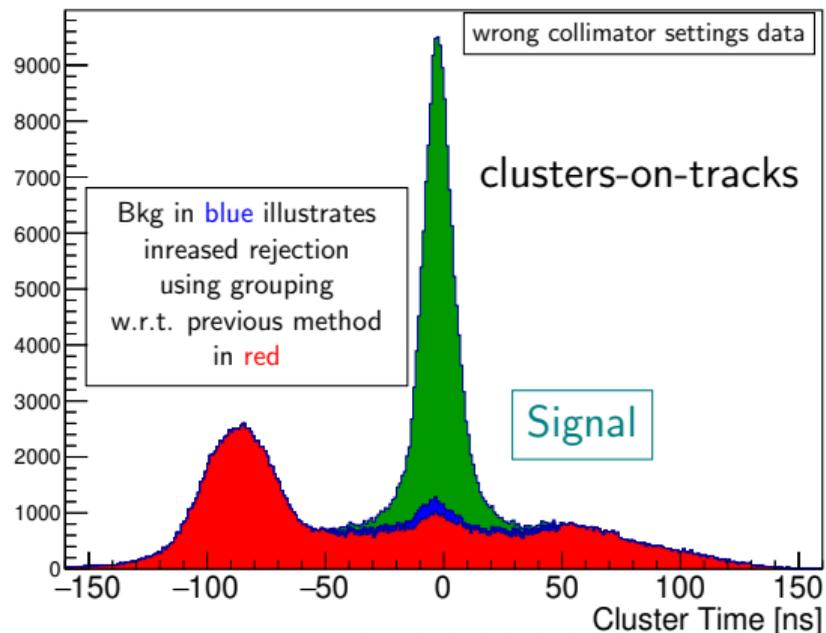


# Background rejection with SVD cluster grouping

- Alternative method to the absolute cut on time to better exploit the hit time information
- Clusters are classified in groups on an event-by-event basis, based on time, and only the signal group is made available for tracking
  - ⇒ Bkg rejection **increased** over the previous method reducing the rate of fake track due to bkg hits by 16%

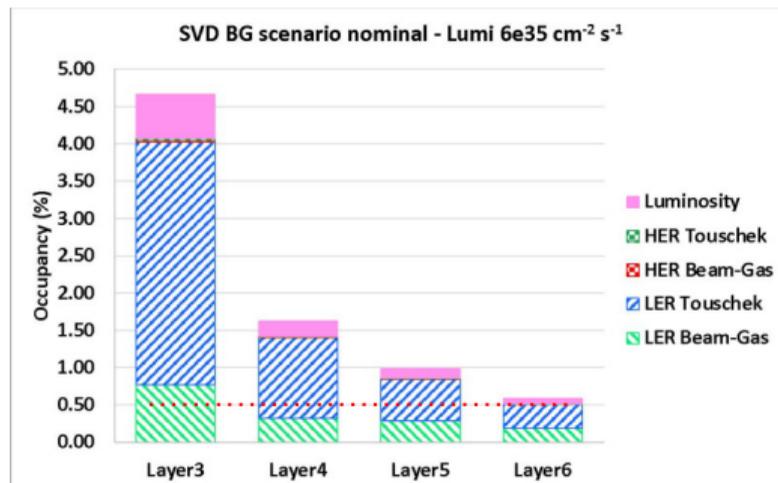


- Along with track-time selection, this method allows to set the SVD occupancy limit at 6%.



# Nominal background prediction : SVD hit occupancy

- Present average hit occupancy is 0.5% at L3
  - well under control.
- Nominal extrapolation to target luminosity shows small safety margin w.r.t. 4.7% limit.
  - With large uncertainty due to future machine evolution and possible interaction region re-design, conservative extrapolation (8.7%) even exceeds 6% limit
- Small safety margin and possible interaction region redesign motivates vertex detector upgrade (S. Bettarini in next talk ...)



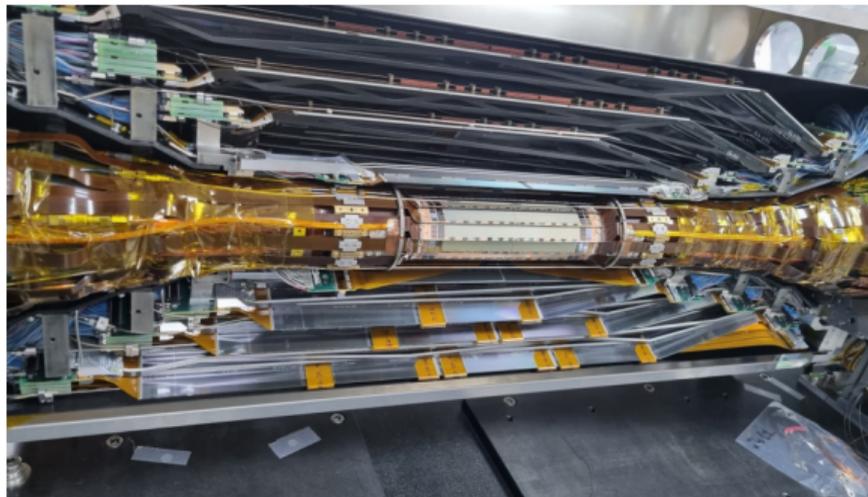
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# VXD re-installation in LS1

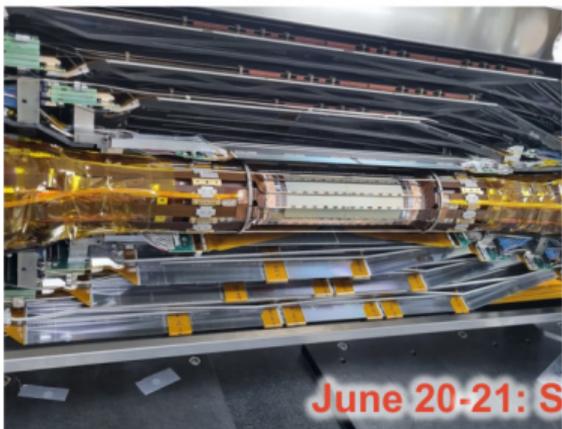
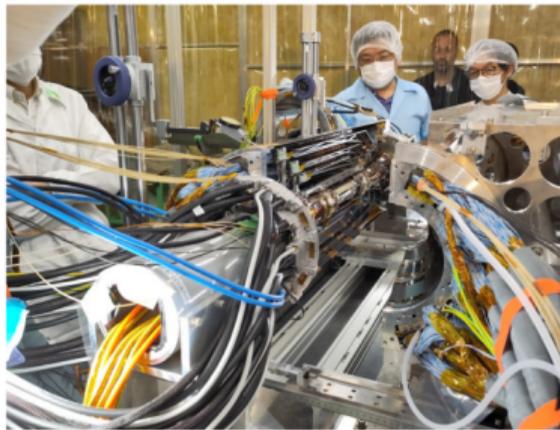
## Intense hardware activities on the SVD for the VXD de-installation/re-installation

May 10	VXD extraction	Belle II
May 17	SVD detachment	activity
June 1	SVD commissioning	in
June 28	New VXD assembly	clean
July 14	New VXD commissioning	room
July 28	New VXD installation	Belle II
ongoing	Functional tests & commissioning with cosmic-ray	



*No major issue on SVD during LS1 activity*

- Upgraded VXD is re-installed during LS1
  - New complete PXD + current SVD



# Summary

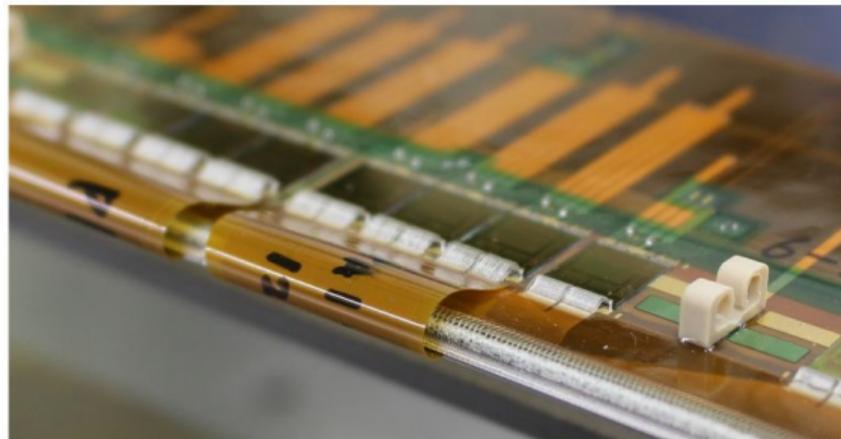
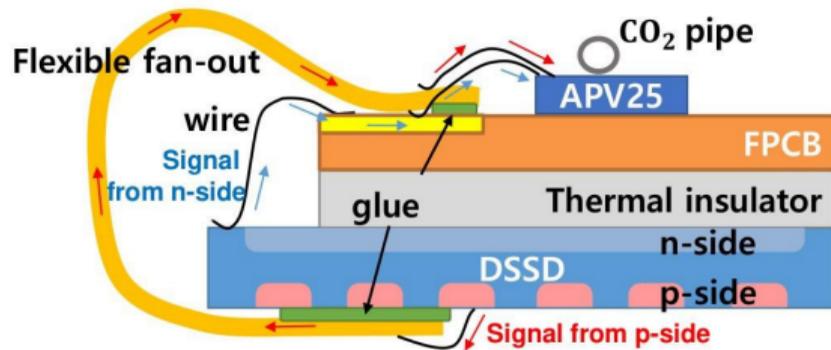
- SVD is performing stably and excellently as expected
  - The design, construction, operation and performance of the Belle II silicon vertex detector is published in the *SVD Technical Paper* ([JINST 17 P11042 2022](#))
- During LS1, VXD is now re-installed at Belle II with new PXD2 and current SVD
  - commissioning with cosmic-ray is ongoing
- Improving SVD software against future high luminosity
  - The accurate SVD time will be crucial in rejecting background and will allow to maintain the current excellent tracking performance
- Background extrapolation to target luminosity shows hit occupancy could exceed our limit, while radiation dose is within safety margin:  
VXD upgrade is under discussion  $\implies$  more robust against high background and matching possible new interaction region now under evaluation

Thank You

# Backup

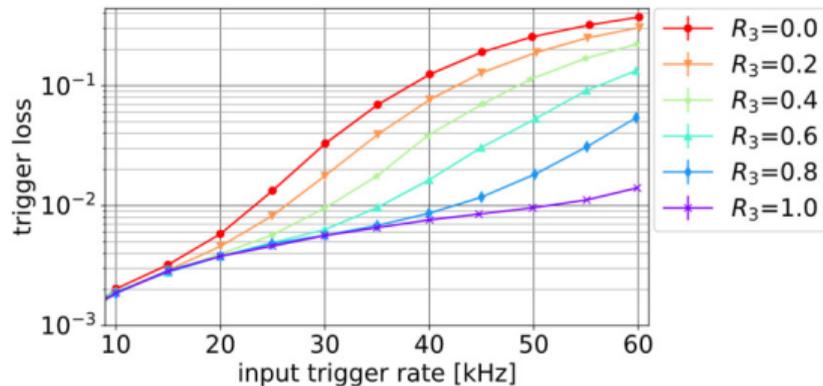
# Origami chip-on-sensor

- Readout chip placed directly on top of Sensor
  - Wrapped flex to read signal from both side
  - Chips are thinned to  $100\mu\text{m}$  to reduce material budget
  - Shorter signal propagation length; smaller capacitance and noise
- Single side cooling tube with  $\text{CO}_2$



# SVD 3/6-mixed DAQ mode

- SVD Data Acquisition consumes time which can attach a significant dead time at higher trigger rates
- Dead time can be reduced by acquiring less SVD samples per event
- Acquiring data with 3-mixed-6 samples is important to reduce the dead time which is useful at higher trigger rate
- 3-mixed-6 sample mode is prepared and tested in 2020c
- 3 or 6 samples are acquired in each event based on trigger jitters:  
Fine TRG (3-sample)  
Coarse TRG (6-sample)

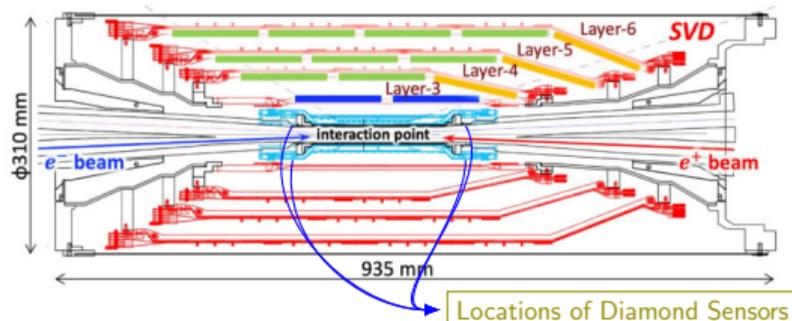


\* 3% dead-time at 30 kHz with  $R_3 = 0$

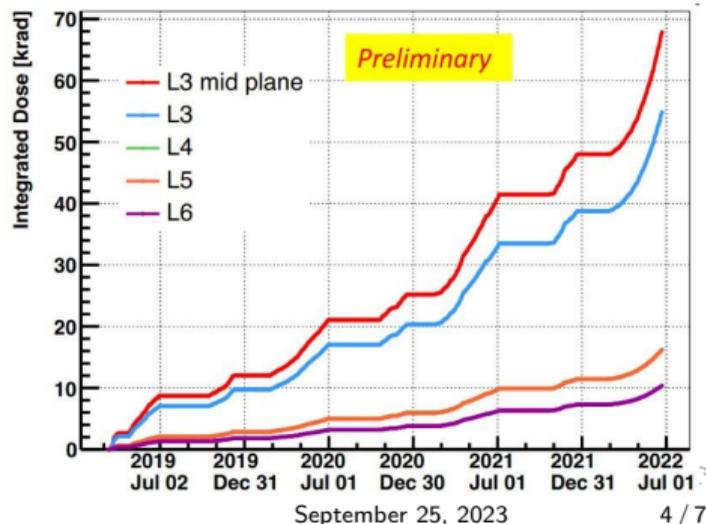
\* 1% dead-time at 30 kHz with  $R_3 = 0.4$

# Integrated radiation dose on SVD

- Dose on SVD is constantly monitored using Diamond sensors and hit occupancy
  - Total integrated damage on L3, 70krad,  $1.6 \times 10^{11} n_{eq}/cm^2$
  - No degradation of detector performance is observed
- Expected radiation damage at nominal luminosity,  $\sim 0.35\text{Mrad}$ ,  $\sim 8 \times 10^{11} n_{eq}/cm^2$  per year
- Irradiation campaign on SVD sensors
  - with 90 MeV  $e^-$  beam at ELPH, Tohoku Univ. July 2022
  - Evaluated radiation tolerance of SVD sensors up-to 10Mrad,  $3 \times 10^{13} n_{eq}/cm^2$
- SVD has a good safety margin for integrated radiation effects: expected to operate well at nominal luminosity for many years

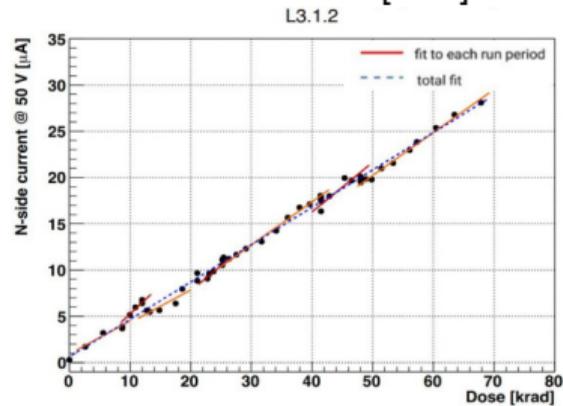
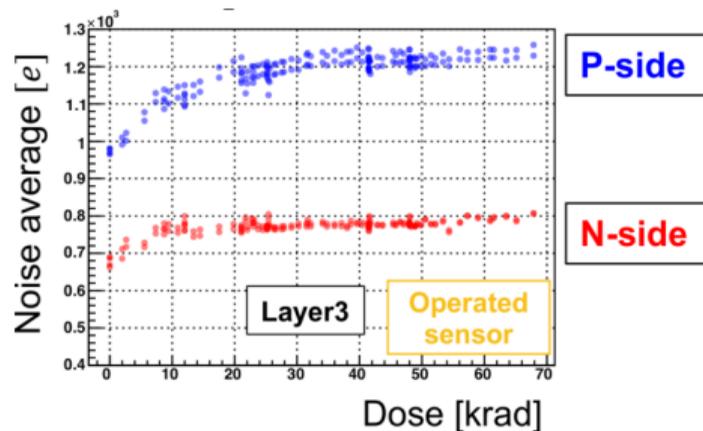


Integrated dose in SVD Layers



# Radiation effects on SVD : strip noise and leakage current

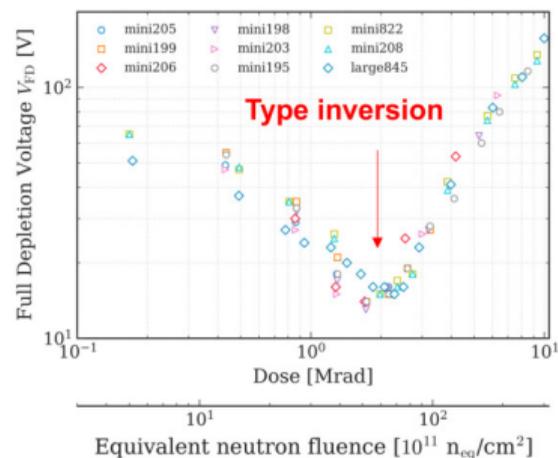
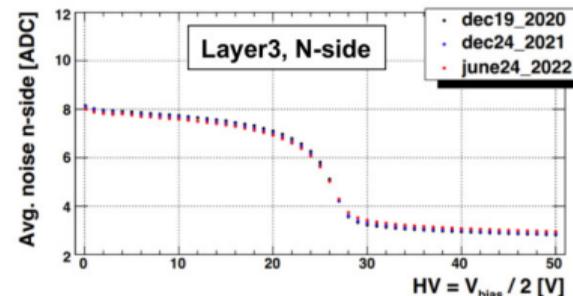
- As expected, noise increases with increased radiation dose
  - increase <20% (30%) for N (P) side
  - dominated by the inter-strip capacitance
  - non-linear due to fixed oxide charges, expected to be saturated
- Linear increases of leakage current with radiation dose as expected
  - proportional to the equivalent neutron fluence (expected from NIEL model)
  - Contribution to noise negligible now due to short APV25 shaping time
  - After 6 Mrad dose strip noise contribution from leakage current would reduce the Layer3 SNR <10



# Radiation effects: full depletion voltage

- ❑ Bulk damage changes the effective doping and the full depletion voltage,  $V_{FD}$ .
- ❑ For operated SVD sensors, the  $V_{FD}$  is measured with N-side noise vs bias voltage.  
⇒ **No change in  $V_{FD}$  observed so far (<70 krad)**

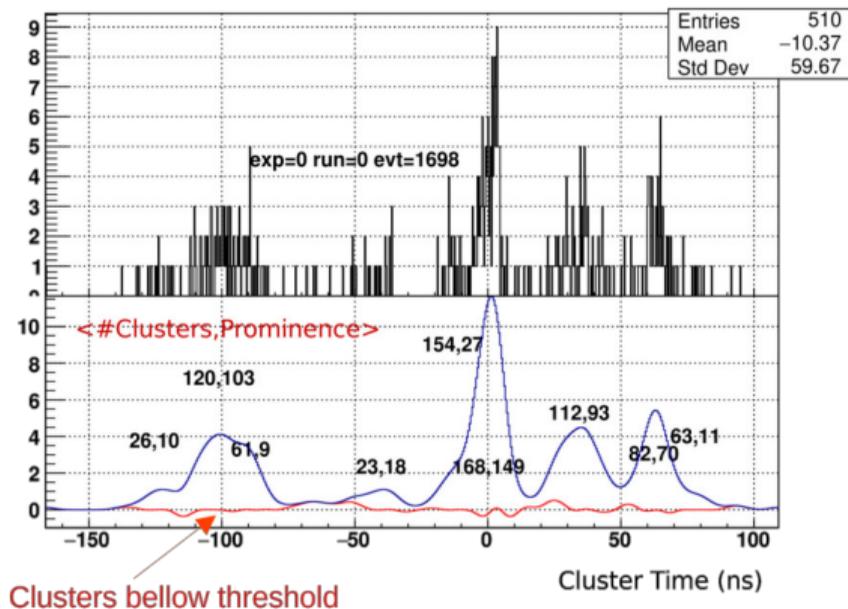
- ❑ In the irradiation campaign, the clear change in  $V_{FD}$  is confirmed with large radiation damage.
  - **Type inversion: 2 Mrad,  $6 \times 10^{12} \text{ n}_{\text{eq}}/\text{cm}^2$**
  - Based on experience on BaBar SVT sensor, SVD sensor will work well above type inversion  
⇒ CCE measurement to confirm it.



\* EPS Slide of Sato-san

# SVD cluster grouping

- We start with an empty histogram of 0.5ns binwidth.
- The for each cluster in a event
  - We **add** a Normalized Gaussian to the histogram.
    - mean is the cluster time
    - width is the cluster time resolution
- Resolutions are already calculated and stored in the payloads along other parameters.
- Resolutions are calculated for 3 types of sensors, 2 sides and for upto clusters size of 6.
- Sensor types are
  - 0 : L3
  - 1 : L456, Sensor 1
  - 2 : L456, Others



Then we find all the peaks by fitting and removing Gaussian from the histogram.